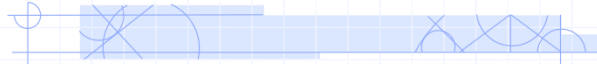




E91B Final Project: Arduino-Based Controller for DJ Software



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Project Outline

- Project: Build a hardware controller for Algoriddim Software's dJay program
 - Allow control of basic interface functions of dJay – turntables and mixer controls
 - Implement control through MIDI over USB – dJay's native control method





Project Outline

- Introduction to djay/DJ software



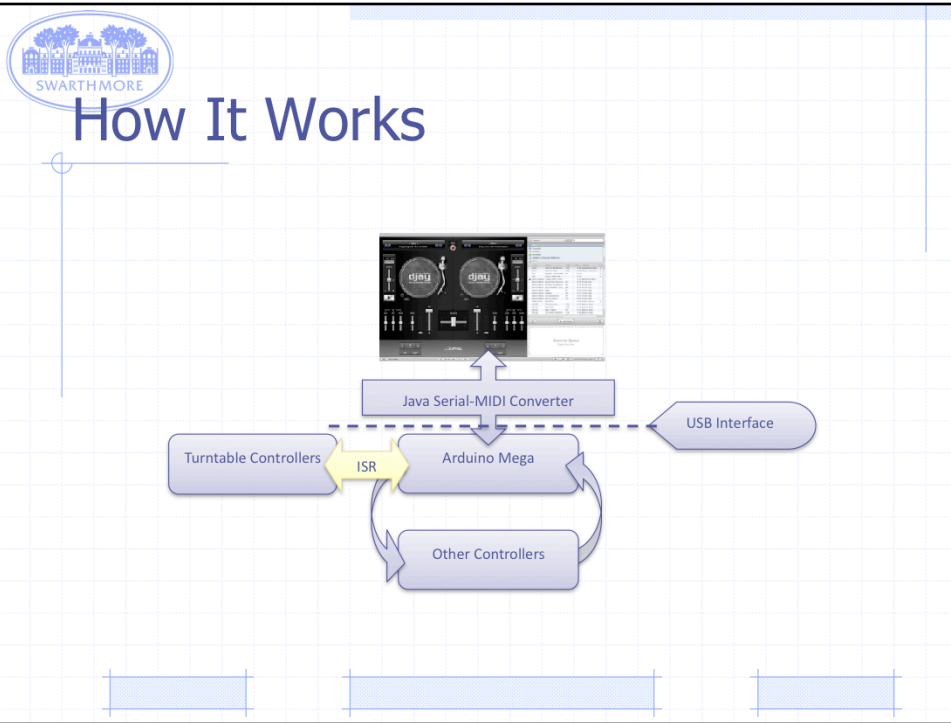
Not shown here:

- Window displaying iTunes music library
- Sampler – allows you to play short segments of audio via buttons



Project Outline

- Goals of Project
 - Turntables: scratching, forward/backwardspin
 - Touch control – turntable controllers are only active when you touch them, just like a real record
 - Crossfader: manual crossfade, left-right autocrossfade, selection of type and duration of crossfade
 - Feedback system?
 - Play/Pause/Reverse Controls
 - Volume, Pitch and EQ controls



Serial to MIDI converter: takes data coming in to serial port through USB, and tells computer that it's MIDI data.

Registers as a MIDI instrument

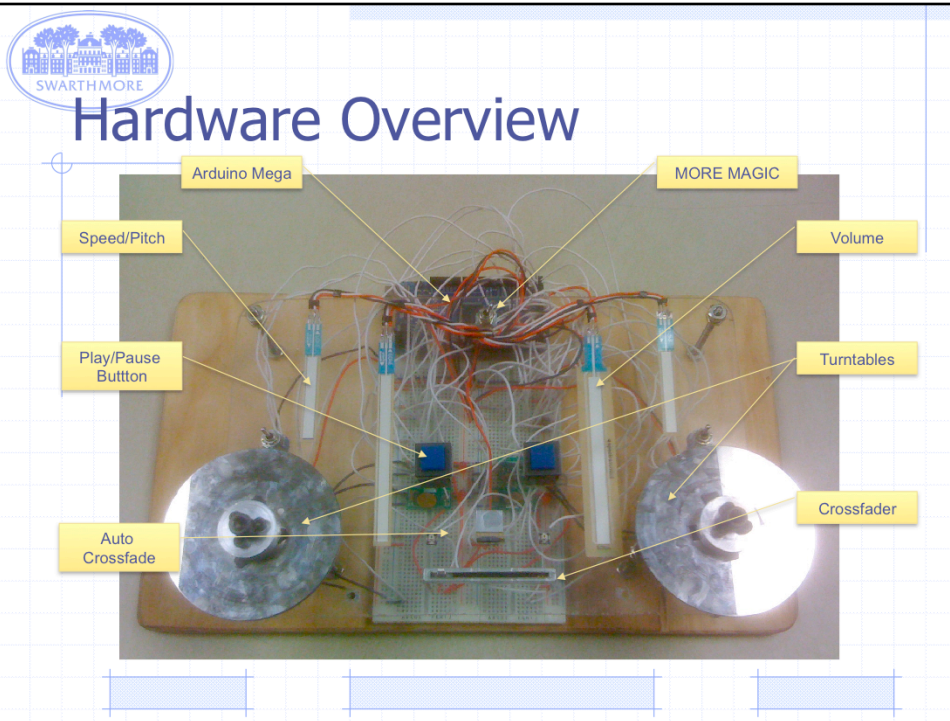
Not my creation – Mark Demers at SpikenzieLabs.com



How It Works

- How MIDI works
 - Serial protocol
 - Typically, a 3 byte message: 0x90 0x2E 0xFF
 - First byte – note type and channel data
 - Second byte – note data
 - Third byte – velocity/setting data
 - Different controls interpret instructions differently

- 8 = Note Off
- 9 = Note On
- A = AfterTouch (ie, key pressure)
- B = Control Change
- C = Program (patch) change
- D = Channel Pressure
- E = Pitch Wheel

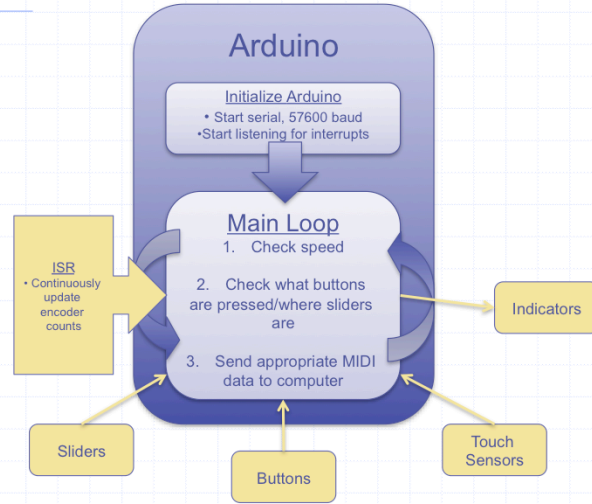


Turntables use capacitive touch sensors to detect touches on platters and on central hubs – platter scratches, hub seeks through song

MORE MAGIC cuts power to capacitive sensor chips – forces recalibration.



Code Overview

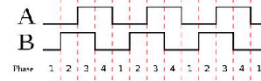




Code Overview

- ISRs & Checking Speed

- Encoders use quadrature output



- ISR: every time there's an edge, update the number of counts

- Checking speed: read current encoder count, wait 25 ms, read current encoder count

- Map into range from 0-63 if moving CCW or 65-127 if moving CW



ISR method is higher resolution than simply looking at rising or falling edges.



Code Overview

- Reading Capacitive Sensors/Buttons
 - Need to encode where we are in the touching process – need to send Note On and Note Off commands

```
void checkTouch(int readChan, int *touch, int *chgTouch) {  
  if (analogRead(readChan) <= 200 && *touch == 0) {  
    *touch = 1;  
    *chgTouch = 1;  
  }  
  else if (analogRead(readChan) <= 200 && *touch == 1) {  
    *chgTouch = 0;  
  }  
  else if (analogRead(readChan) > 200 && *touch == 1) {  
    *touch = 0;  
    *chgTouch = 1;  
  }  
  else {  
    *chgTouch = 0;  
  }  
}
```

- 1) If we weren't touched previously, and now we are, then record that we ARE being touched, and that this is a new and exciting experience for us.
- 2) If we were touched previously, and we're still being touched, then record that we're still being touched, but it's lost its initial glitz.
- 3) If we were touched previously, but all of a sudden we're not anymore, then complain! We didn't know we had it so good until it was gone!
- 4) If we weren't touched previously, and that's not a new event, then nothing happens.



Code Overview

- Reading Sliders/Dials

- Read voltage from wiper of potentiometer with ADC

- Map from voltage to MIDI with map()

```
void faderPos() {  
  voltage = analogRead(4);  
  curFader = map(voltage, 5, 550, 0, 127);  
  if ((curFader < (prevFader - 5)) || (curFader > (prevFader + 5))) {  
    Serial.print(0xB2, BYTE); // Note on, MIDI channel 3  
    Serial.print(0x08, BYTE); // Play controller 08  
    Serial.print(curFader, BYTE); // Controller setting  
    prevFader = curFader;  
  }  
}
```

- Some smoothing implemented to remove noise from low-quality slide potentiometers





Code Overview

- Sending MIDI
 - Turntables:
 - Touching: 0x90/0x80 (note on/off on correct channel – touch or release turntable) – 0x2E – 0xFF (unused)
 - Spinning: 0xB0 (control change on correct channel) – 0x10 (coarse pan control) – 0x__ (speed)
 - Buttons:
 - 0x90 – 0x__ – 0xFF (unused)
 - Sliders:
 - 0xB0 (control change on correct channel) – 0x__ (slider number) – 0x__ (position)

All data is sent via serial using `Serial.print()` command



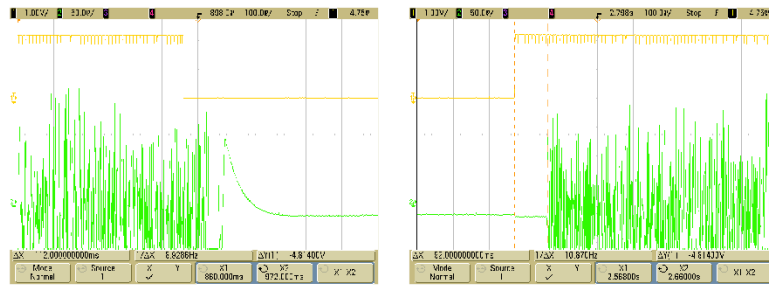
Did It Work?





Did It Work?

- Control Latency



– Latency is average 103 ms – 4x latency of serial-MIDI converter alone.

Industry standard for latency is < 10ms – should be less than 50 ms

Probably due to clunky Arduino code



Did It Work?

- Problems
 - Final Product
 - Lack of precision in control
 - Capacitive touch design is hard!
 - Production process
 - Lack of communication/documentation
 - Supply issues



Future Work

- More Controls!
 - Samplers, EQ, Cue Points, Looping, Sync/Beatmatch
 - Visual feedback for non-tactile sliders
- More resilient systems
 - Packaged product – allow for transport
- Lower latency – have the Arduino present to computer as MIDI device
- Learn how to DJ





Conclusion

- Thanks to:
 - Prof. Cheever, Ed Jaoudi for help with project
 - Frederik Seiffert at Algoriddim Software for assistance with MIDI communication
 - Bourns, Inc. and ALPS for component samples
- Questions?